Name Mrs. MONISHA PATHAK.

Designation Assistant Professor (Stage3).

Department Instrumentation Engineering, Jorhat Engineering College, Jorhat-785007, Assam

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Area of Specialization: Instrumentation and Control

Educational Qualification:

1. PhD Pursuing(Thesis Submitted), Department of Electrical Engineering, Dibrugarh University.

2. MTech (2015) Specialization: Power and Control, Department of Electronics & Electrical Engineering, IIT Guwahati .

3. BE (2000) Instrumentation Engineering, Jorhat Engineering College, Dibrugarh University.

Professional Experience:

From 02/03/ 2007 - till date: Faculty, Jorhat Engineering College.

Courses Taught:

Transducers, Industrial Instrumentation, Process Control, Modern Analytical instruments.

Projects guided: UG: More than 45, PG: 02.

Membership:

- Life Member of Instrument Society of India
- Life Member of Biomedical Society of India

Sponsored Research Project:

Project	Funding Agency	Amount	Duration	Current
Title				Status
Robust Control of	TEQIP-III of Assam	2.25 Lakh	1.5 years	Completed
Uncertain Robotic	Science &Technology			
Manipulator	University.			

Publications;

Title of the paper	Publication	Date/Year of Publication	National or International Journal/Conference				
1. T. Rasul ¹ , M. Pathak² , <i>Control of nonlinear chemical process using sliding mode control</i> , 2016 1st International Conference on Power Electronics, Intelligent Control and Energy Systems (ICPEICES 2016), 4-6 July' 2016, Delhi Technological University, Delhi.							
<i>Tracking of Robotic</i> Material Sciences,	<i>Manipulator</i> ", Ir Instrumentation, tion Technology (nternational Confere Electronics, Comm	<i>us Terminal Sliding Mode Control for Trajectory</i> ence on Innovative Research In Applied Physics, unication, Electrical, Power Control, Computer), 22nd and 23rd December, 2016, USIC, Gauhati				
	cal and Electronic		g Process using Sliding Mode Control, Advanced EEE), Vol 3, Issue 5, 2016, pp. 349-353, Krishi				
4. M. Pathak¹ , A. Saikia, Dr. M. Buragohain, "Trajectory Tracking of Robotic Manipulator using Terminal Sliding Mode Control," International Conference On "Electronics Communication, Robotics, Data Mining, Information Sciences and Electrical Engineering"(ERDIE-2019), 27th April 2019, Jawaharlal Nehru University, New Delhi.							
	Sliding Mode Tech		ront Steer Angle and Direct Yaw Moment Using 1 Conference on ETEES-19, 29-30 th March, 2019,				
	front steering. Ad		d on unified chassis control with electronic stability n Electrical & Electronics Engg , KrishiSanskriti				
Integrating Active Front	t Steer angle and I	Direct Yaw Moment	ased Vehicle's Lateral Stability Enhancement by Control. National Conference on Recent Advances 2020, ASTU, Guwahati, Assam.				
	<i>pproximation</i> ", In	ternational Journal	Control of Robot Manipulator Trajectory Tracking of Engineering and Advanced Technology (IJEAT)				
			sed Sliding Mode Adaptive Controller for Tracking				
Control of Robot Manip 2249-8958 (Online), Vo			ineering and Advanced Technology (IJEAT) ISSN:				

FDP/ Workshop attended:

Sl No.	Name of the Course/ Summer School	Place	Duration	Sponsoring Agency
1	Lasers: Fundamentals and Applications	NITTTR, Chandigarh	18/07/2022 to 22/07/2022 (One Week)	MHRD, Govt of India
2	Fiber Optic Testing and Measurements	NITTTR, Chandigarh	from 21/03/2022 to 25/03/2022 (one Week)	MHRD, Govt of India
3	Nanotechnology for electronic and photonic devices	NITTTR, Chandigarh	06/06/2022 to 10/06/2022 (One Week)	MHRD, Govt of India
4	Analytical Techniques for Material Characterization	NITTTR, Chandigarh	07/03/2022 to 11/03/2022 (one Week)	MHRD, Govt of India
5	Industry 4.0	NITTTR, Chandigarh	10/01/2022 to 14/01/2022 (one Week)	MHRD, Govt of India
6	Refresher Course in Nanoscience and Nanotechnology	NITTTR, Chandigarh	13/06/2022 to 24/06/2022 (Two Weeks)	MHRD, Govt of India
7	Nanosensors & Devices	NITTTR, Chandigarh	22/08/2022 to 26/08/2022 (One Week)	MHRD, Govt of India
8	SmartMaterialsProcessingandApplications	NITTTR, Chandigarh	25/07/2022 to 29/07/2022 (One Week)	MHRD, Govt of India